# TJHSST Computer Systems Lab Senior Research Project Three Dimensional Collision Detection for N Solids Using OpenGL 2006-2007 Richard Hooper

#### Abstract

Collision detection is a very useful concept, it is used in various applications from surgery to manufacturing to video game design. My project aims to create an efficient algorithm for detecting collisions so that it can be used in a gaming environment. The objects in collision will be simple solids, and multiple will be put in a space to monitor their interactions. The first step is simple 2D collisions followed by more complex 3D collisions.

### Introduction

In this project, I plan to create an efficient algorithm for 3D collision detection. This project has value, because there are many different applications for collision detection, and in game development, as with all other fields, efficiency is of extreme importance.

Collision detection is the concept of first detecting possible collisions, then contact, and then determining how to react to the collision. I intend to create an efficient algorithm that would detect collisions, so that the interactions of multiple solids could be modeled at once. The first step is to create a simple 2D algorithm that would model collisions as a prototype, followed by a simple 3D algorithm. This would then be optimized or redesigned, and then the number of solids in the given space would be increased, and the time taken and accuracy would be tested. The goal is to have the number of solids in space to be in the thousands, but the first benchmark would be in the hundreds.

# Development

The workplan for the project is as follows: write a 2D algorithm, then write a 3D algorithm, then optimize the 3D algorithm or rewrite it to meet my time constraints.

# **Expected Results**

I would expect the results to be a 100% success in respect to all collisions and contact made, and the speed in which the program executes should not experience any noticeable slowages. This means that in the end, there would be a large number of solids, hopefully at least one thousand would be able to interact seamlessly.